* In this paper a Fault Tolerant system for the attitude estimation of an Unmanned Aerial Vehicle (UAV) using low cost magnetometers, accelerometers, and gyroscopes, implemented in an Inertial Measurement Unit (IMU) is proposed

超长语句和of后特长的描述是允许的

* in the literature for the solution of Fault Detection, Isolation and Reconfiguration (FDIR) problems

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