* In this paper a Fault Tolerant system for the attitude estimation of an Unmanned Aerial Vehicle (UAV) using low cost magnetometers, accelerometers, and gyroscopes, implemented in an Inertial Measurement Unit (IMU) is proposed

超长语句和of后特长的描述是允许的

* in the literature for the solution of Fault Detection, Isolation and Reconfiguration (FDIR) problems

在关于错误检测隔离重构问题的文献中

* doesn’t seem to be backwards compatible with any LTE network older than Release 13

似乎并不能向下兼容xxxx